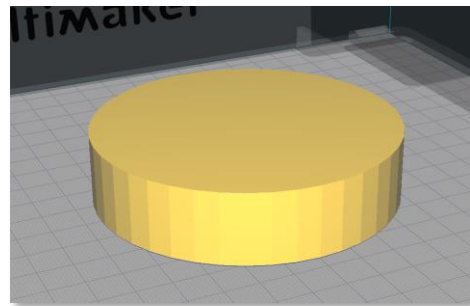
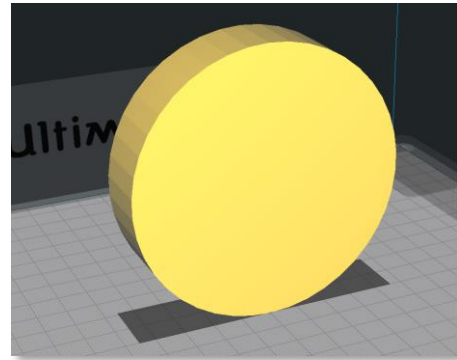


Determining Optimal Print Orientation Using GPU-Accelerated Convex Hull Analysis

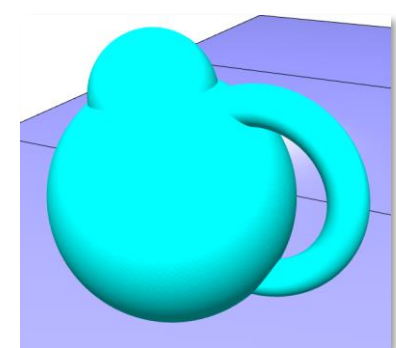
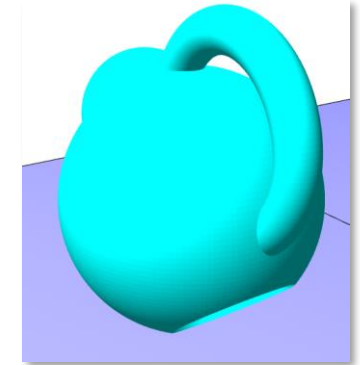
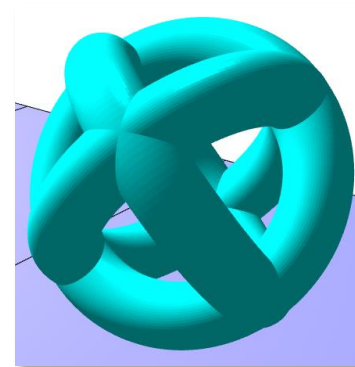
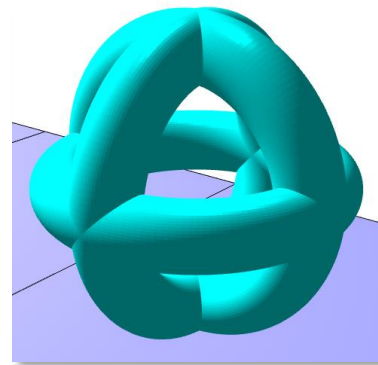
Charles Wade, Breanne Crockett, Michael Borish, and Robert MacCurdy

How do we identify a “good” orientation for 3D printing?

Trivial Cases:



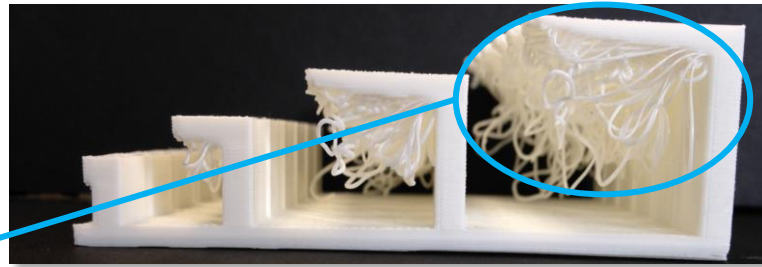
Non-Trivial Cases:



What intuition are we using?

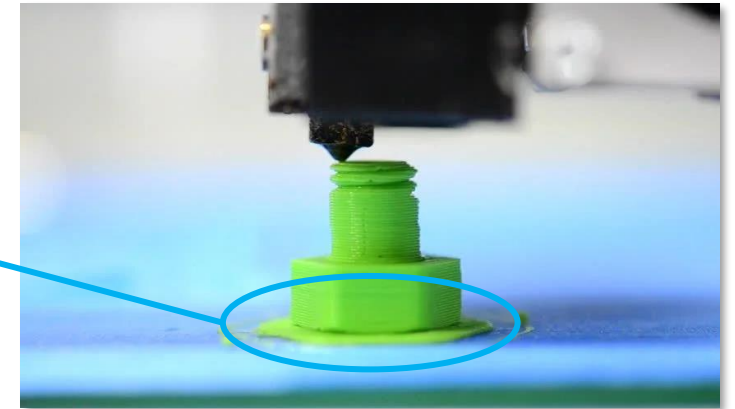
Minimize

(overhang/ supports)



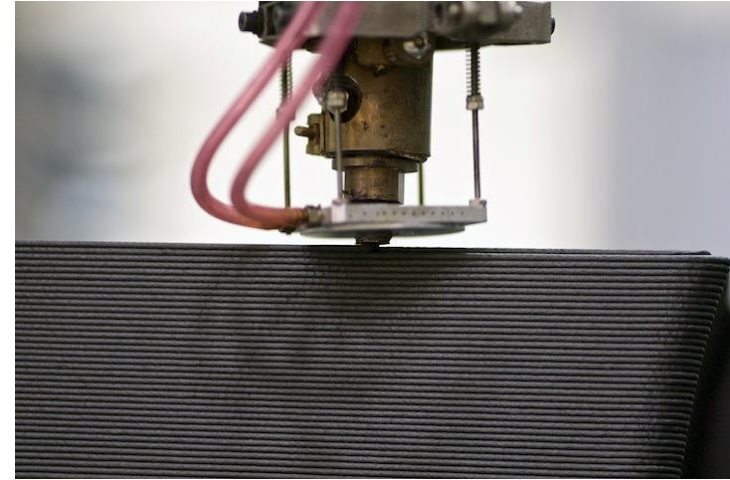
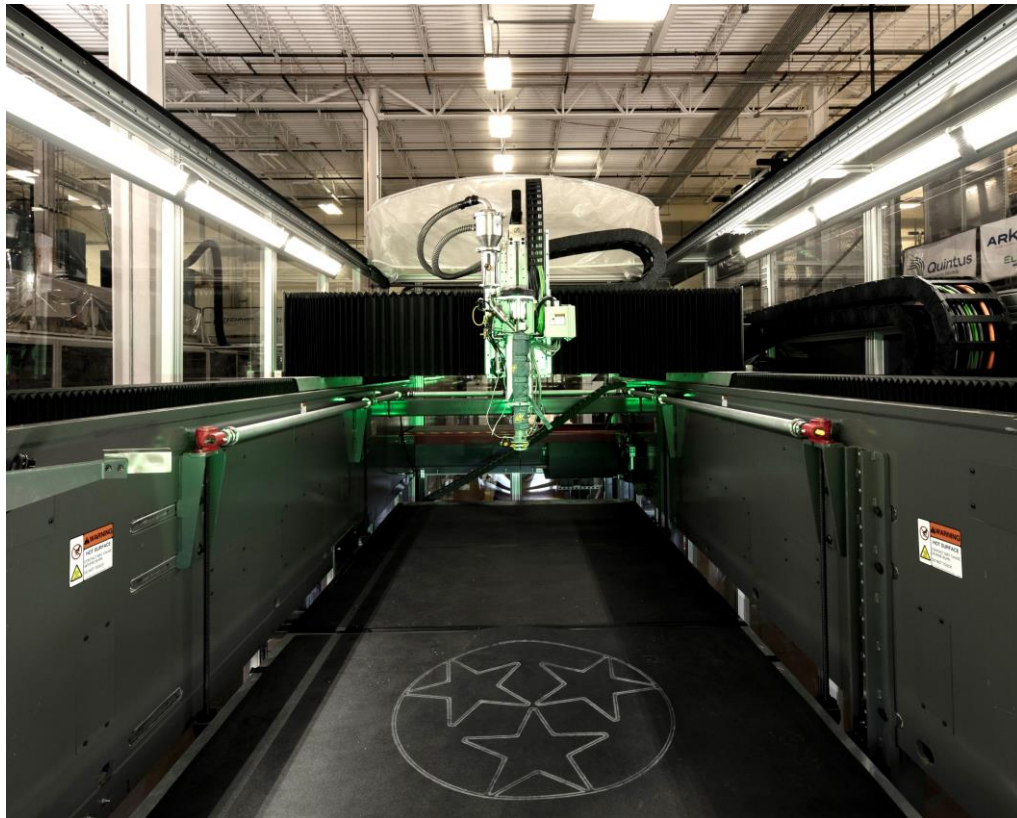
Maximize

(adhesion to build surface)

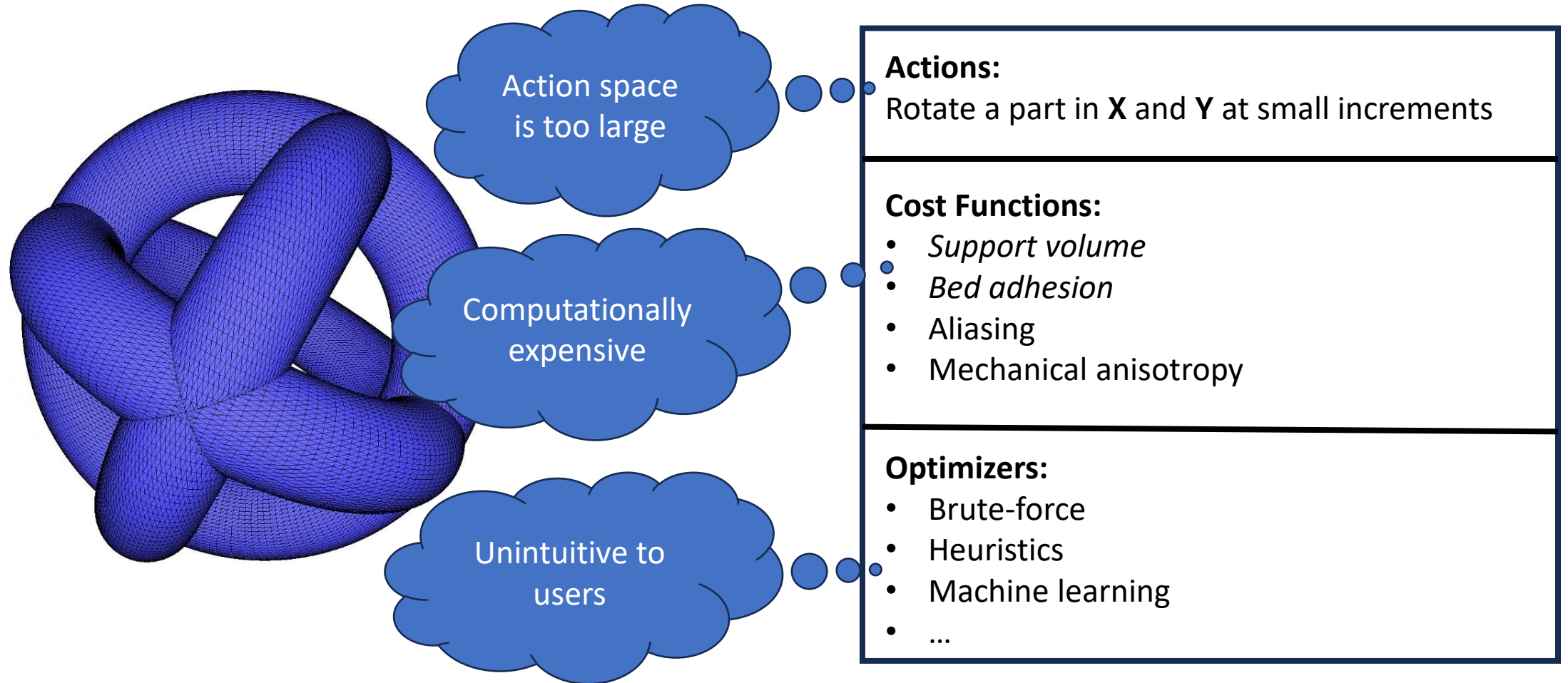


Result:
Improve probability of a successful quality print

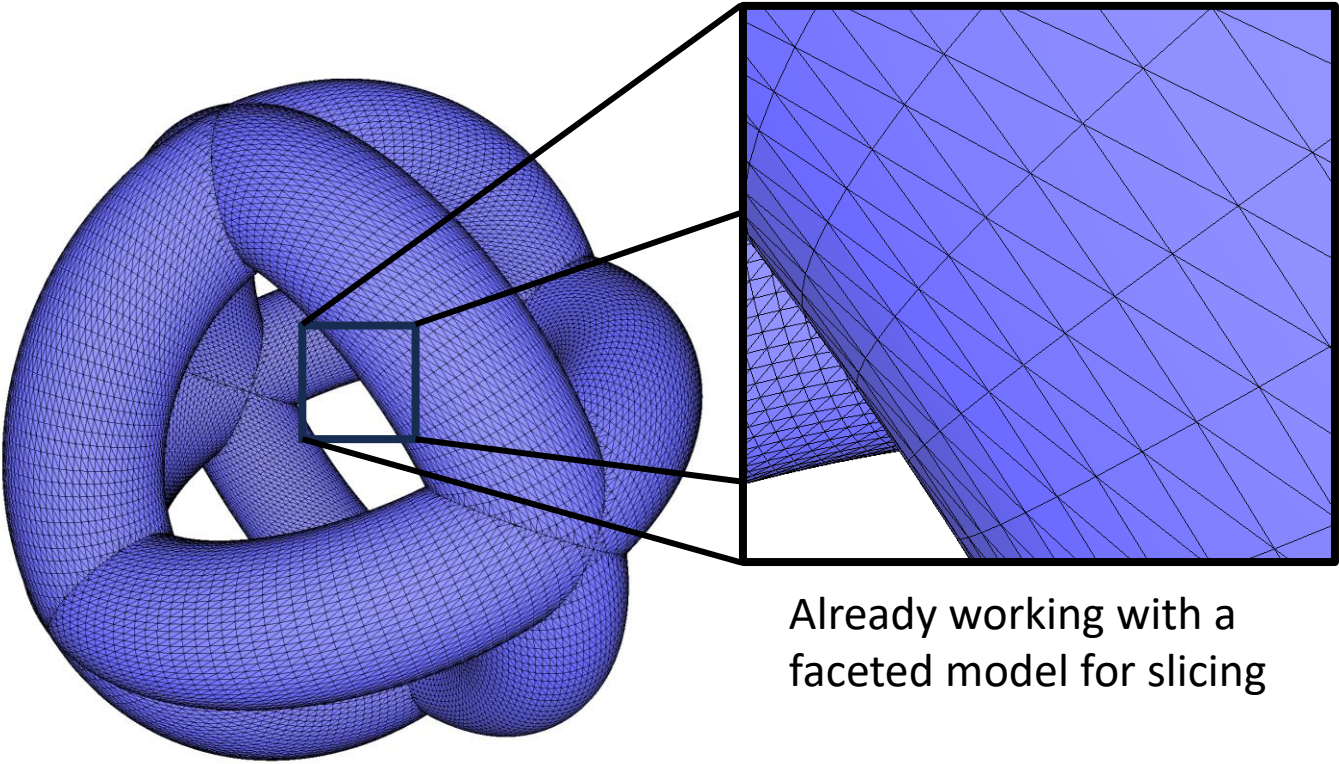
Our focus on large format FFF



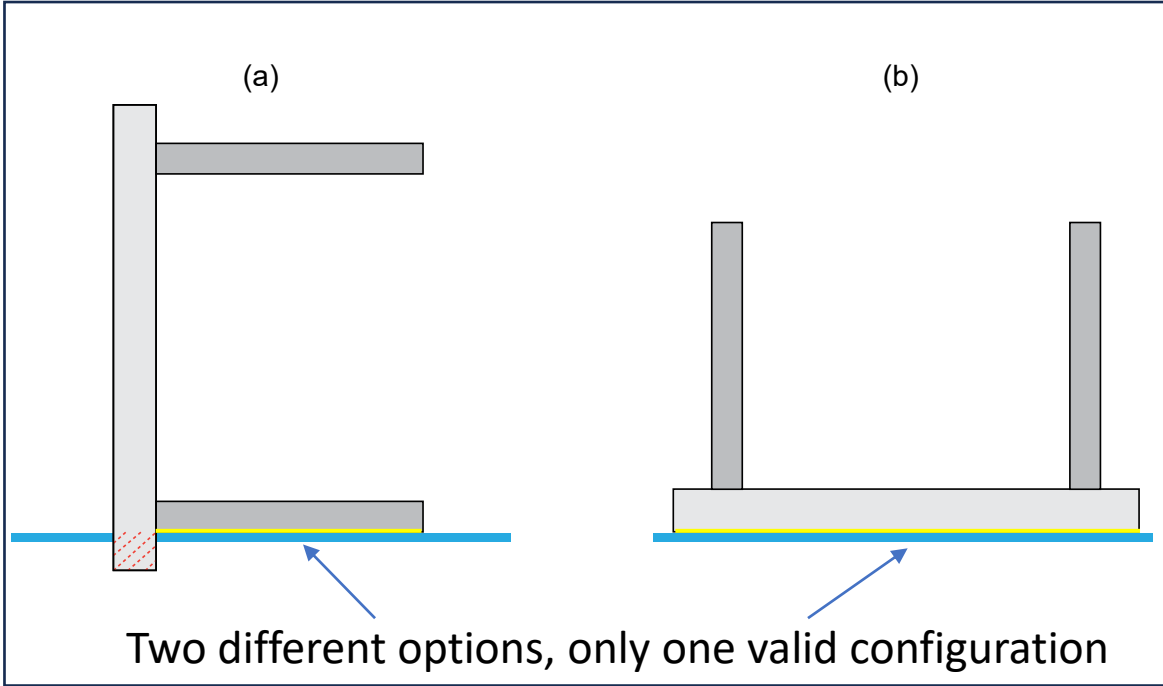
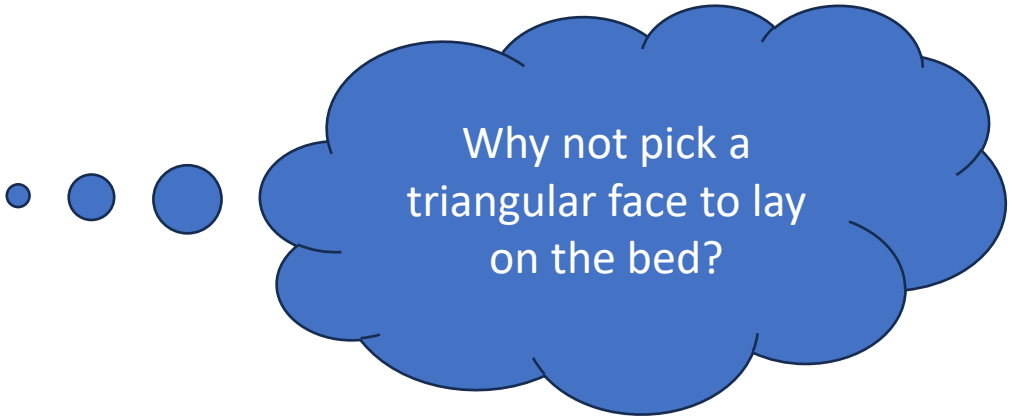
Existing Automated Approaches



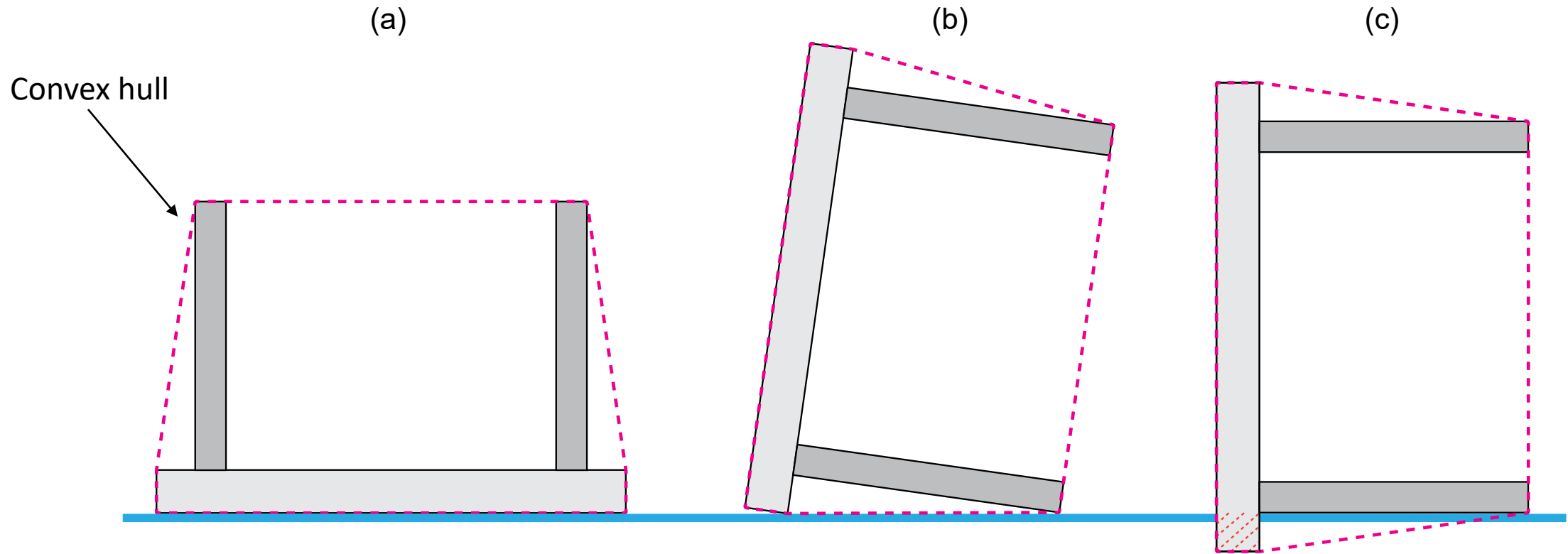
Reducing the action space



Already working with a faceted model for slicing

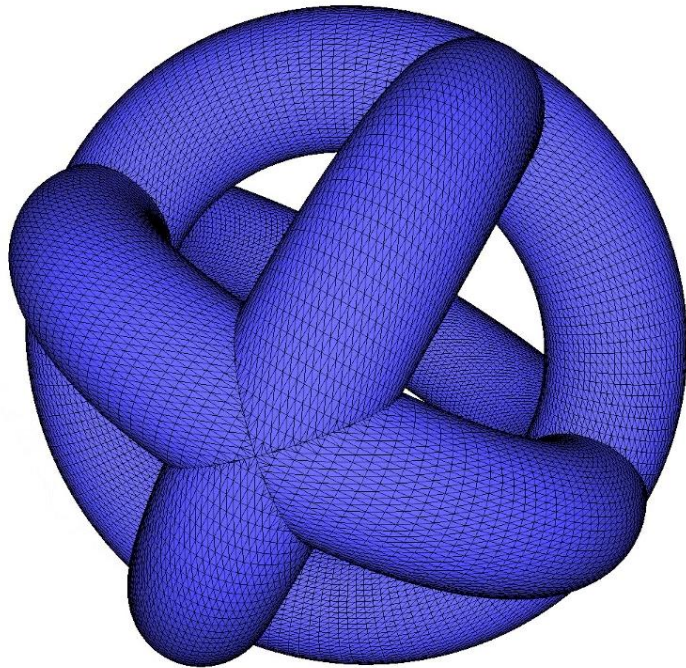


Picking only valid options

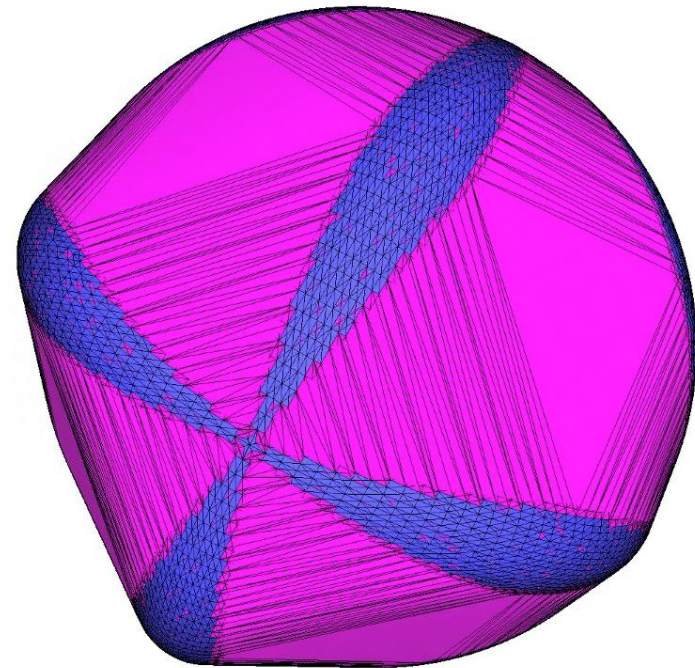


Lemma:
Any face on the convex hull is a non-intersecting orientation

Convex hulls in 3D



Original



Convex Hull

Compute hull using Quickhull algorithm:
Average runtime is $O(n \log n)$

Progress

Actions:

Rotate a part in **X** and **Y** at small increments

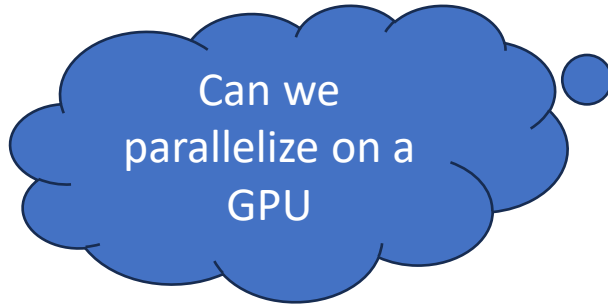
Cost Functions:

- Support volume
- Bed adhesion

Optimizers:

- Brute-force
- Heuristics
- Machine learning

Progress

**Actions:**

Pick any face on the convex hull

Cost Functions:

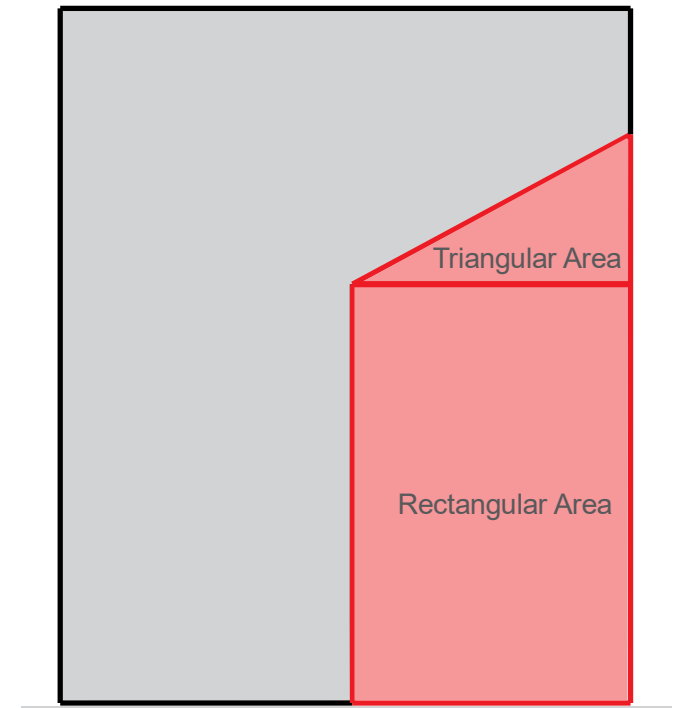
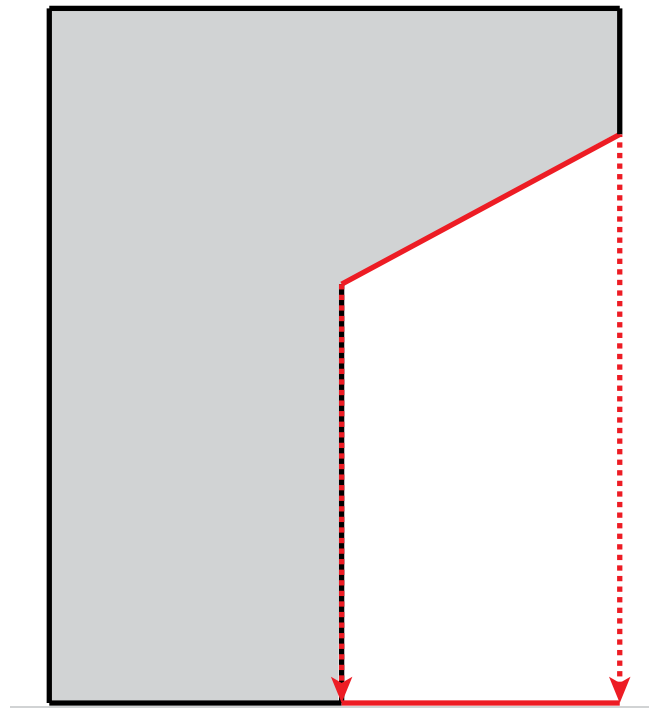
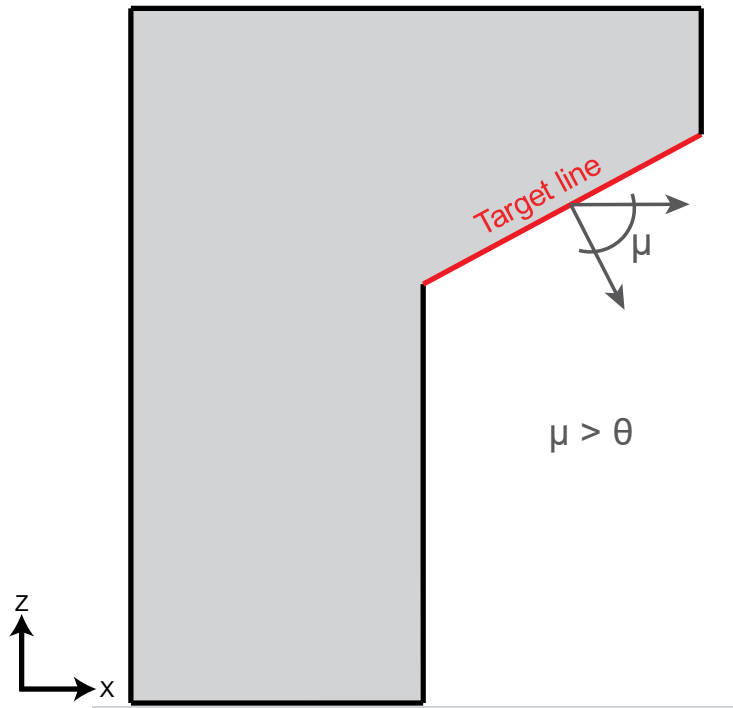
- Support volume
- Bed adhesion

Optimizers:

- Brute-force
- Heuristics
- Machine learning

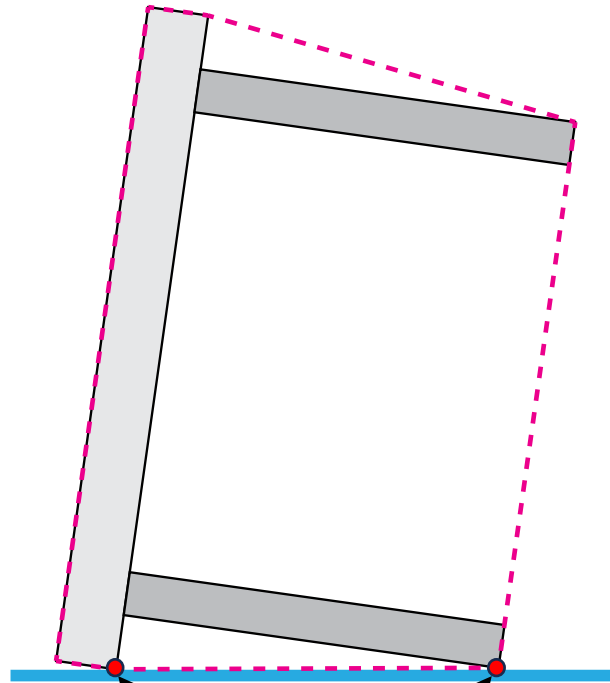
Computing Support Volume

For every line/ triangle:

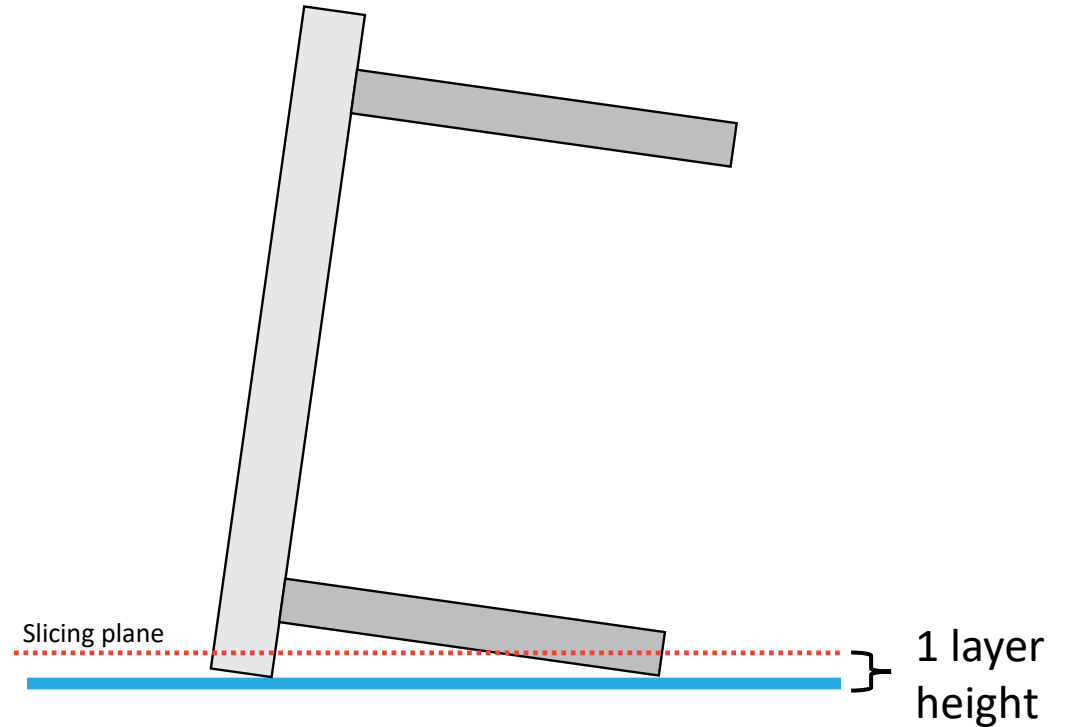


Repeat for all triangles in mesh to get total supports volume

Computing Surface Area on Build Plate

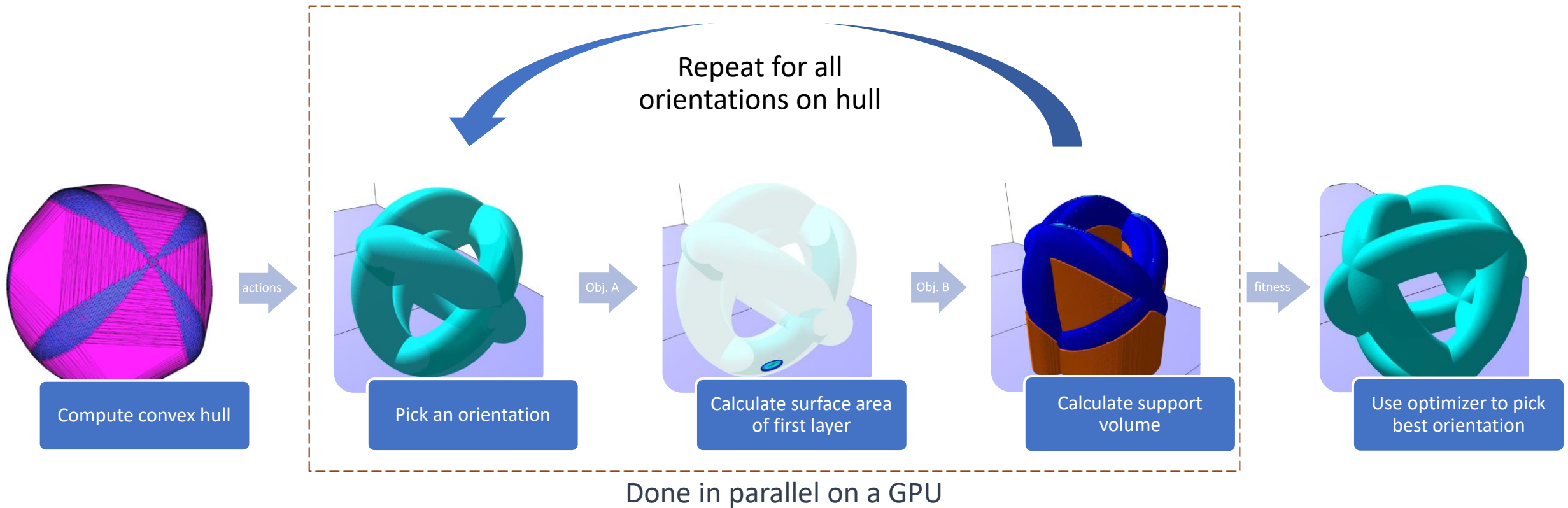


Contact at single points
Yields no area



Slicing at 1 layer height
Yields real area

Putting this together



Progress

Actions:

Pick any face on the convex hull

Cost Functions:

- Support volume
- Bed adhesion

Optimizers:

- Brute-force
- Heuristics
- Machine learning

Progress

Actions:


Pick any face on the convex hull

Cost Functions:

- *Support volume- on GPU*
- *Bed adhesion- on GPU*

Optimizers:

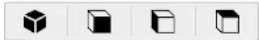
- Brute-force
- Heuristics
- Machine learning



How can we make
an interactive tool
for the user?



Currently Manipulating: None



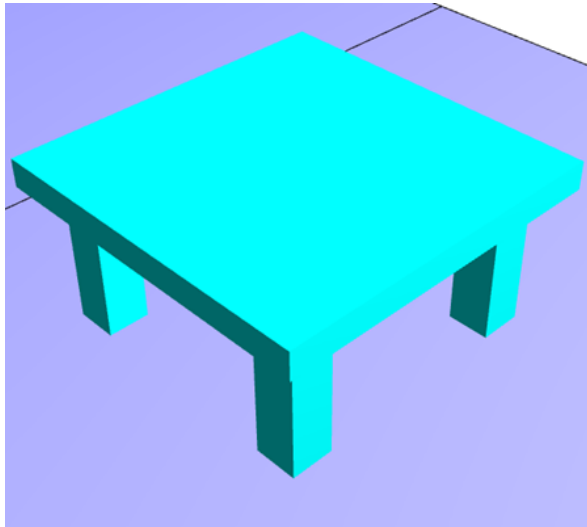
- Printer
 - Material
 - Profile
 - Experimental
- Machine Setup
 - Dimensions
 - Auxiliary
 - Machine Speeds
 - Acceleration
 - G-Code
 - Embossing Support

Search for setting...
LPAM_G3in

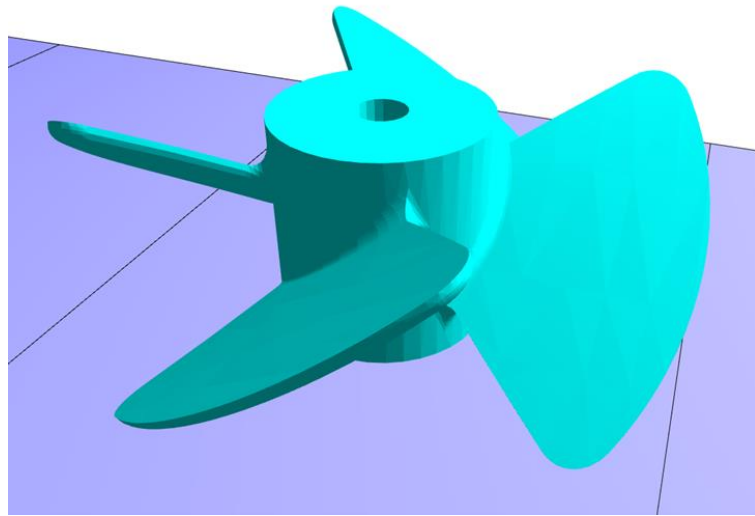
Currently searching in: C:/Users/ujw/Desktop/Slicer 2 Configs/ for additional setting files

Status area for displaying messages or errors.

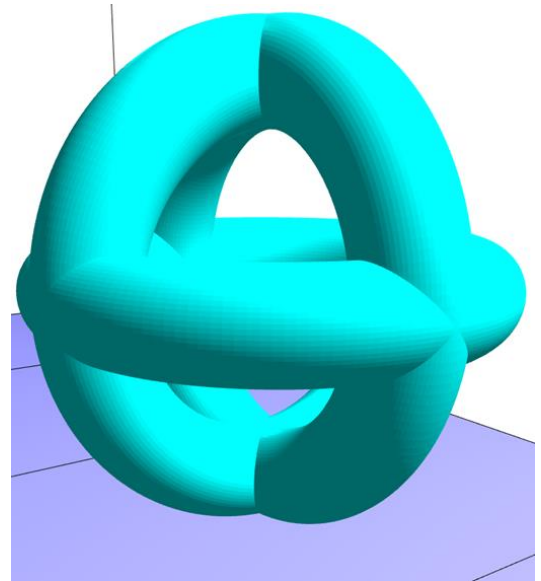
Case Studies:



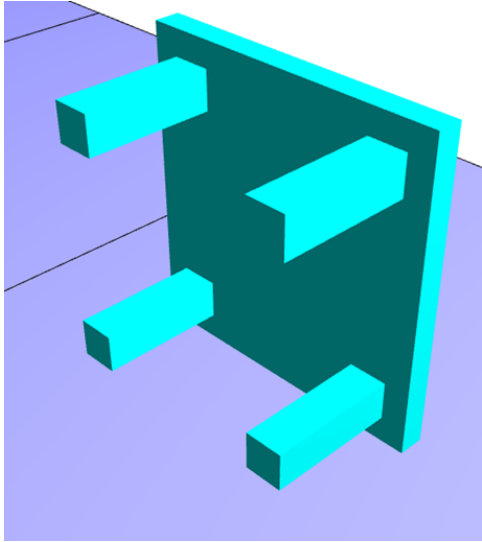
Simple 4-legged table



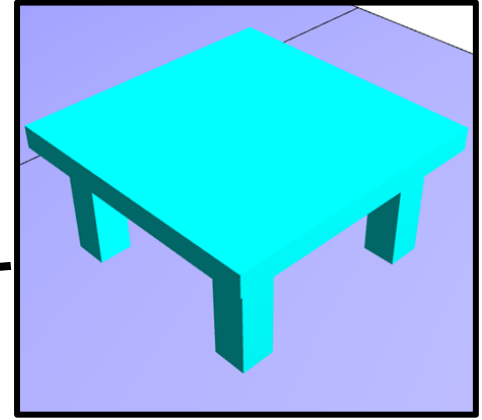
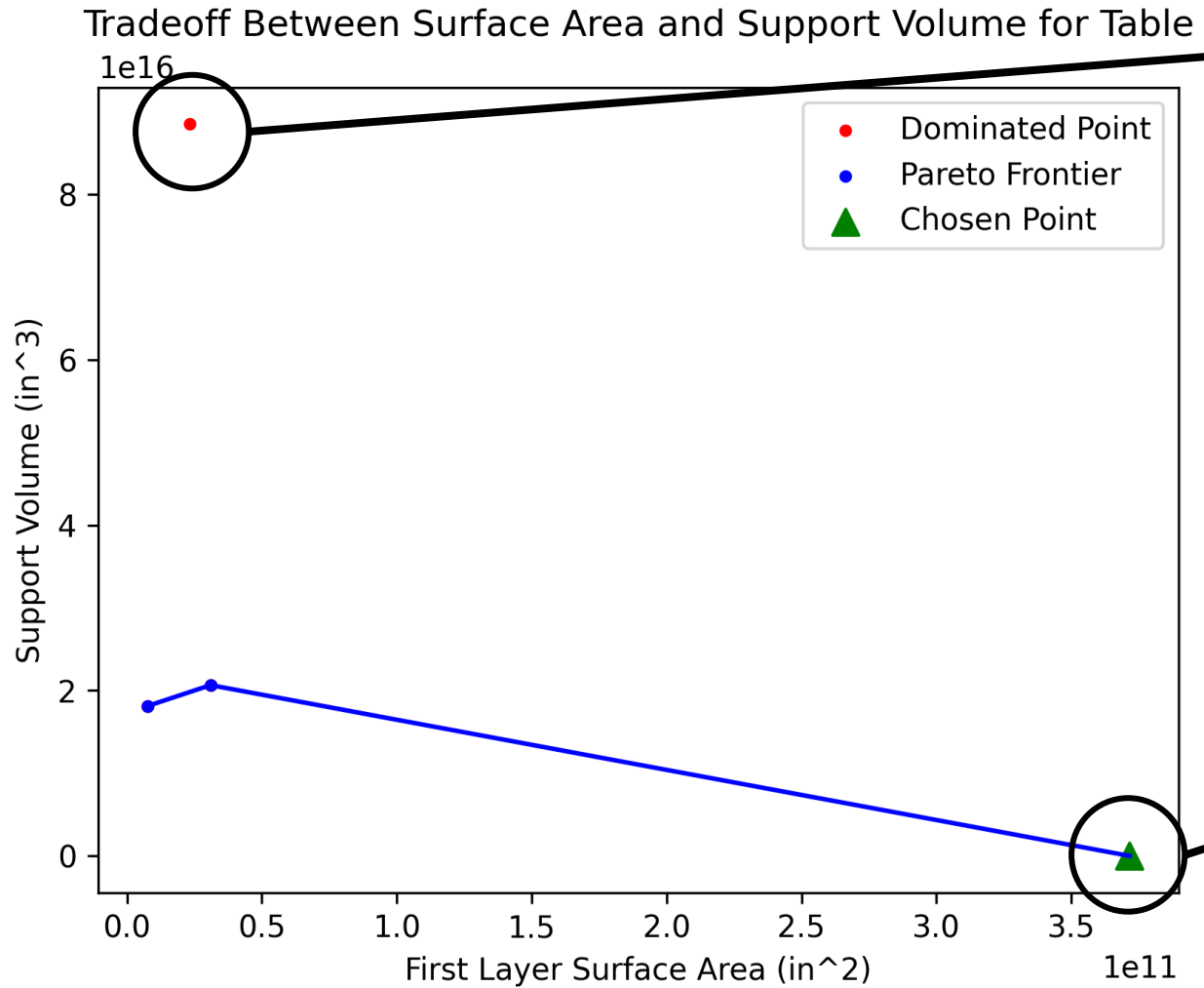
Propeller



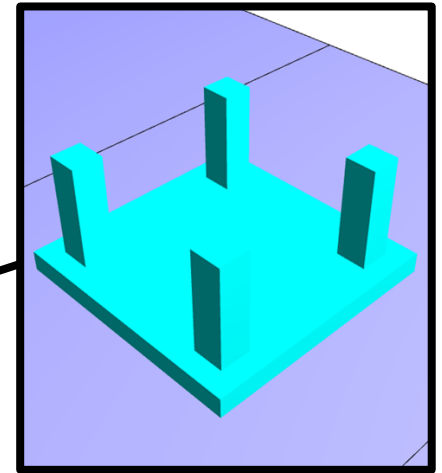
Rings



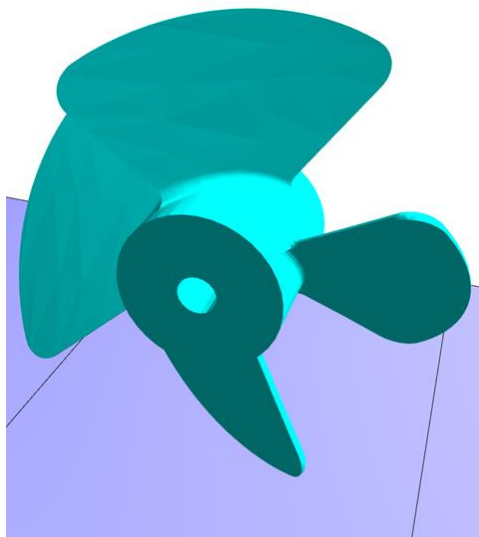
Initial random orientation



Worst orientation

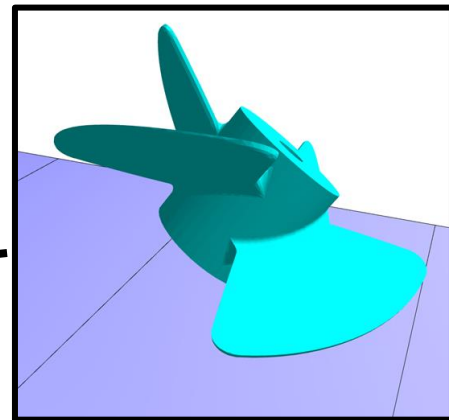
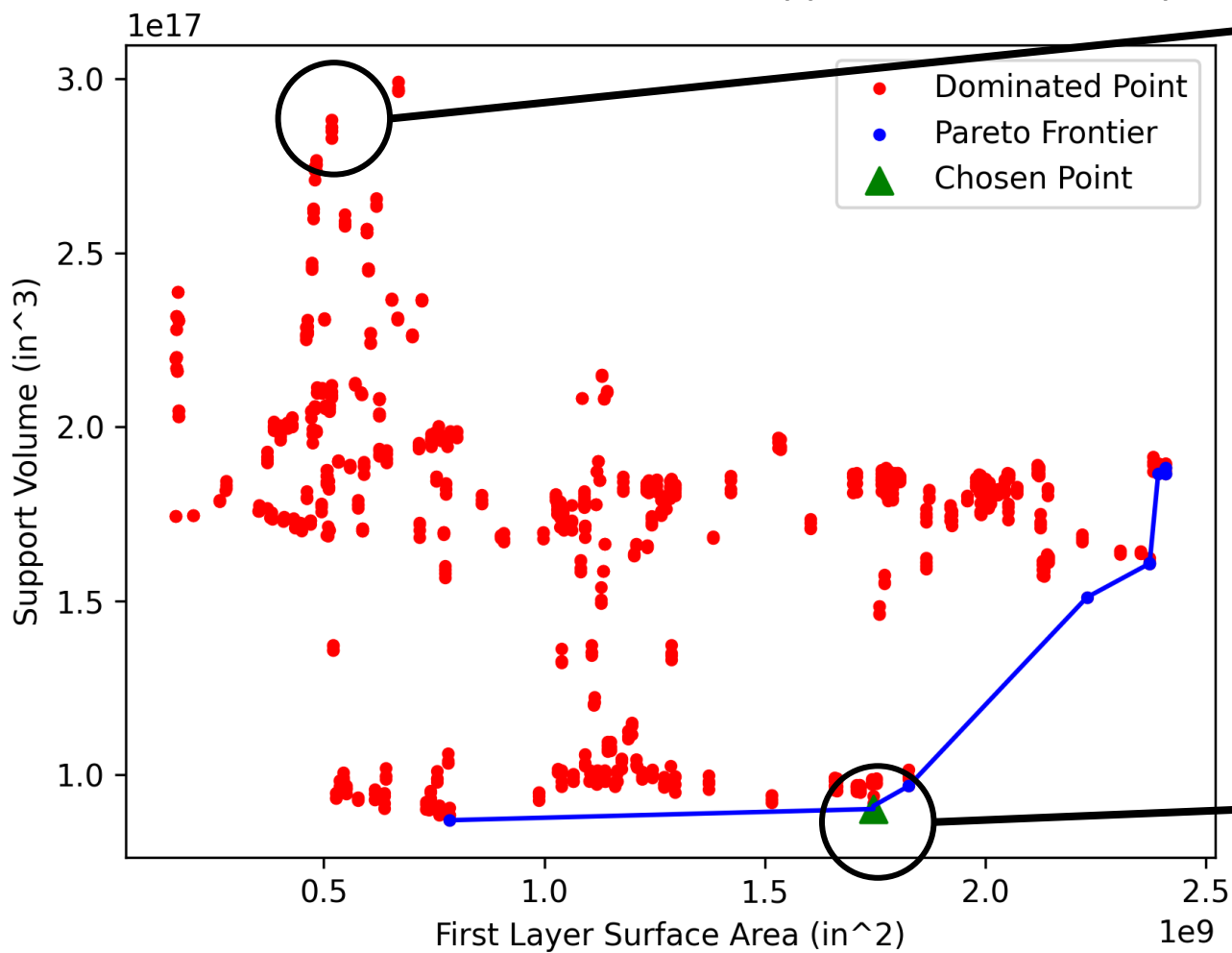


Best orientation

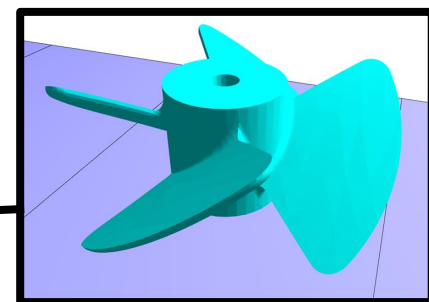


Initial random orientation

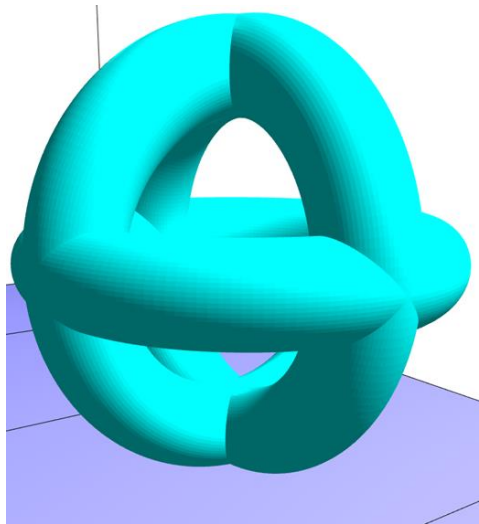
Tradeoff Between Surface Area and Support Volume for Propeller



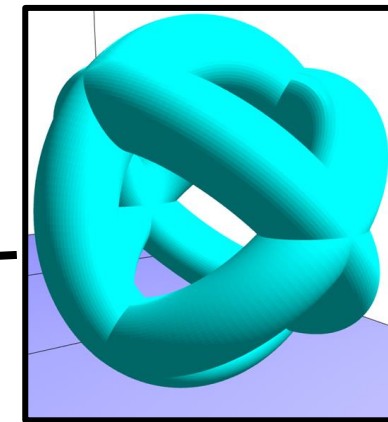
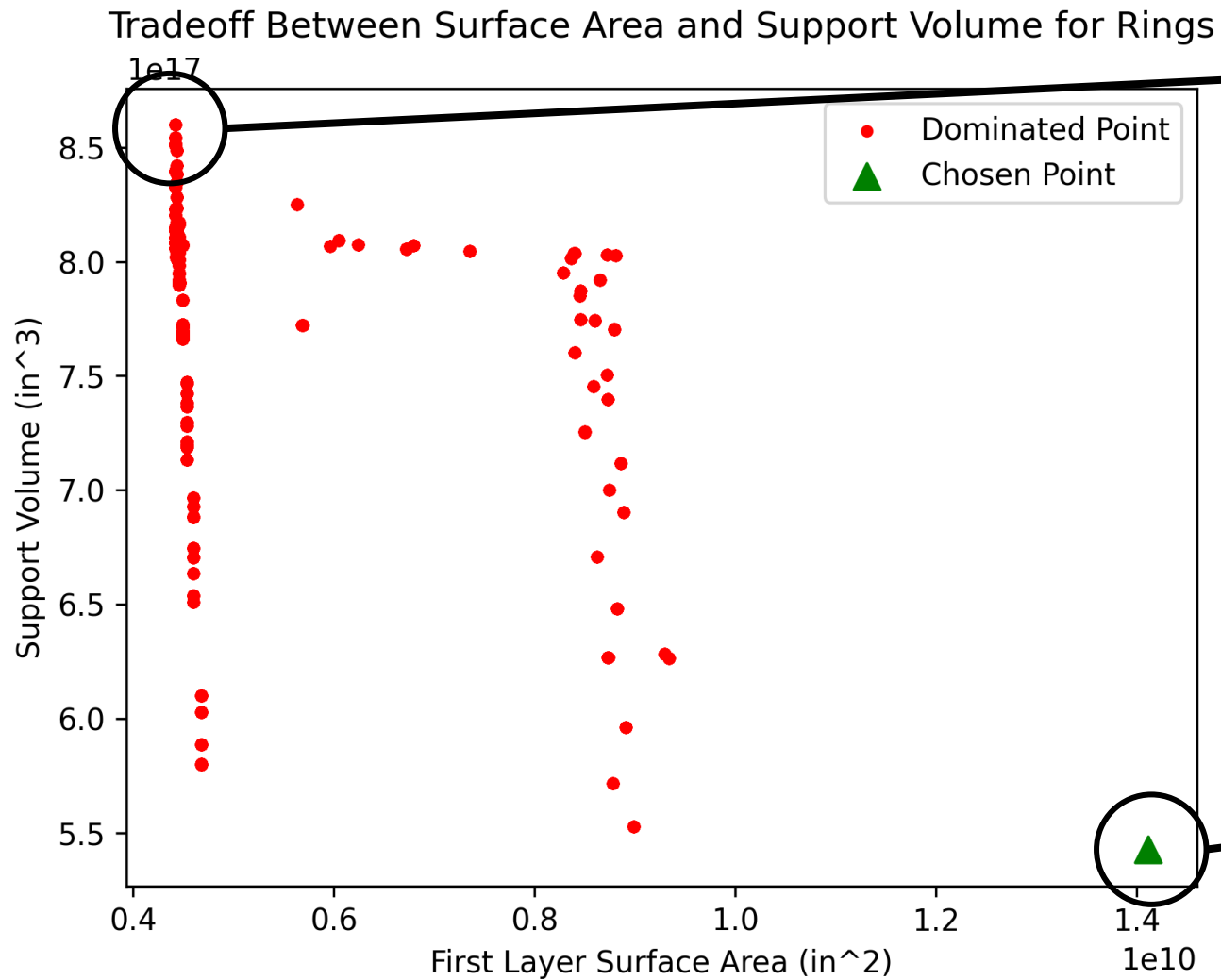
Worst orientation



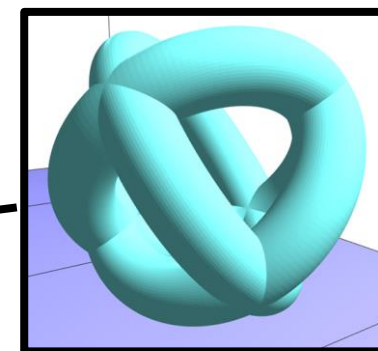
Best orientation



Initial random orientation



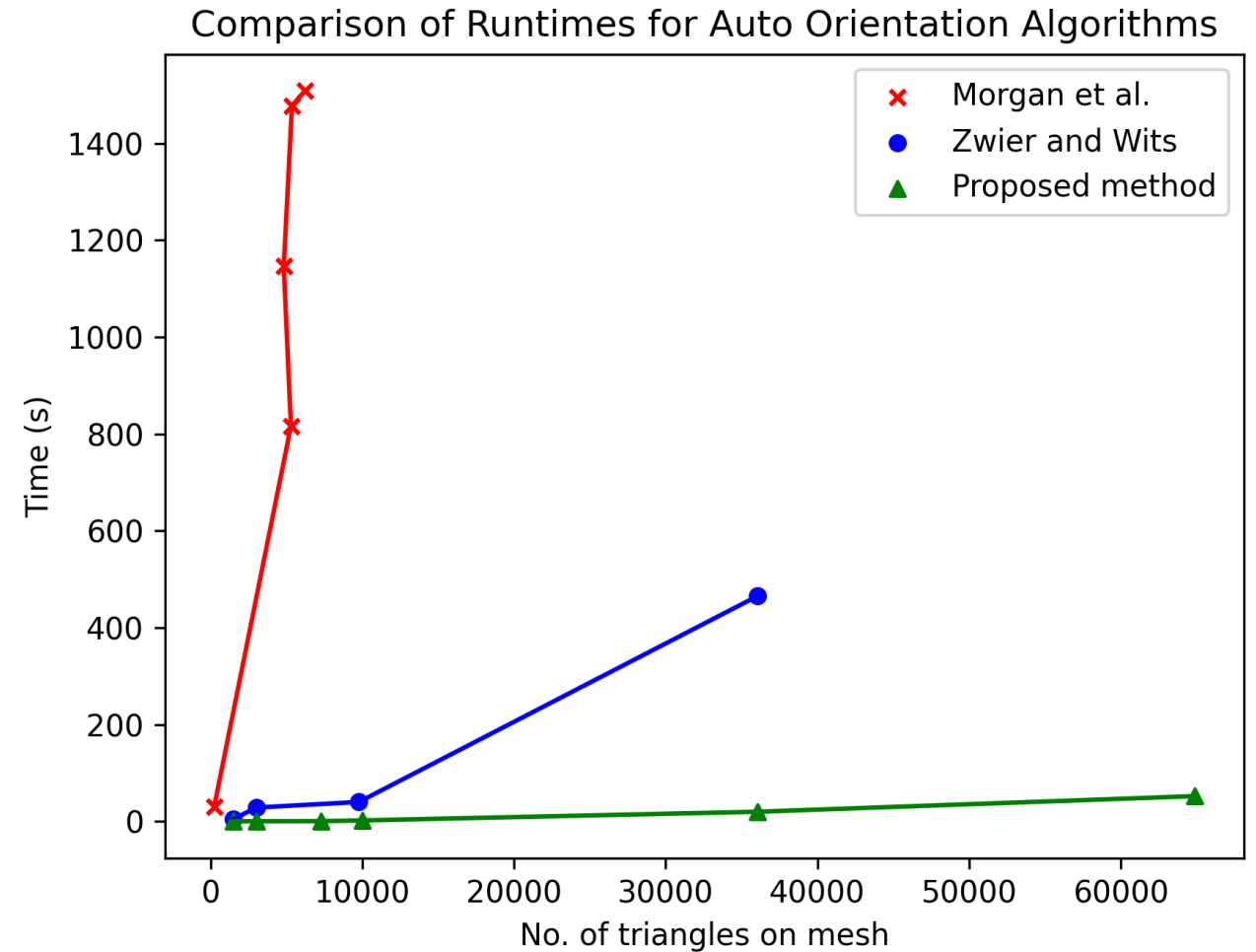
Worst orientation



Best orientation

Runtime Results

Design	Triangular Faces	Computation Time (s)
	7,286	0.75
	64,896	11.9
	299,256	22.6
	675,528	66.7



Want to try it yourself?

Integrated into **ORNL Slicer 2** as an interactive tool.

